**Research Paper Summary**

**Title:** Vision-Based Path Coordination for Multiple Mobile Robots with Four Steering Wheels Using an Overhead Camera

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**Date:** (publication date in YYYY-MM)

**Link to paper:** link to my github repo

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Section 1 - Overall Idea

* given A resources, B constraints, solve problem C in order to achieve result D
* look at abscract, and conclusion for A, B, C
* look intro for result D, or the reason behind it

Section 2 - Methodology

* how the paper proposes to solve the problem / achieve desired result
* what frameworks / systems / methods?

Section 3 - Applications

* Related work - what can be done with it?

Section 4 - Future Development

* How can the work be expanded

Section 5 - Questions

* Any questions I have on the paper

Section 6 - Anything Else

* Any other comments on the paper that don’t fit in the other sections